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2 *Research paper*

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4 **Detector for monitoring potential bleeding during electron**
5 **intraoperative radiotherapy**

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16
17 **Abstract**

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19 *Purpose:* The aim of this work is to develop a bleeding detector integrated into the
20 acrylic circular applicators for specific mobile linacs. Thus, a bleeding detector has been
21 developed based on a capacitive sensor to be used with plastic applicators, as in the case
22 of LIAC HWL from Sordina IORT Technologies SpA. According to the clinical impact,
23 we have selected 0.5 cm as the minimum depth of fluid that should be detected.

24 *Methods:* An experiment was developed using water-simulating blood. Two setups were
25 considered: non-beveled applicators with 7 cm and 10 cm diameter. Measurements were
26 done for applicators 0° and 45° tilted, both with respect to the horizontal surface, in
27 order to mimic the worst clinical scenario according to the irradiation gantry and
28 applicator bevel angle. The behavior of the detector under irradiation was analyzed and
29 the impact of the stray radiation on the detector was also evaluated.

30 *Results:* The detector was able to distinguish the presence of liquid at a minimum height
31 of 0.5 cm. A linear behavior was obtained for both setups. We have also verified that the
32 LIAC HWL radiation does not affect the measurements nor does the detector interfere
33 with the stray radiation. The bleeding detector is a quasi-digital capacitive sensor with
34 low-cost, high linearity, and easy to install.

35 *Conclusions:* With this detector it is possible to perform a continuous monitoring of the
36 liquid measurements even during the irradiation phase. Thus, it can operate not only as
37 a pre-treatment detector but also as a continuous one.

38
39 **Keywords:** Intraoperative radiotherapy, bleeding, electrons, capacitive sensors

40 **I. INTRODUCTION**

41 Intraoperative radiotherapy is an extended technique being applied to a wide range of
42 specific diseases in exclusive mode or combined with external radiotherapy. For
43 example, it is suitable for the treatment of several malignancies [1], such as: the central
44 nervous system, head and neck, breast, lung, gastric, pancreas, bile duct, gallbladder,
45 colorectal, retroperitoneal, extremity and trunk soft-tissue, bone, gynecologic,
46 genitourinary and pediatrics.

47 Intraoperative radiotherapy with mobile linear accelerators is a well-established
48 modality that is gaining popularity because, thanks to the significant improvement in
49 technology, it can be used in a conventional surgery room without specific shielding
50 conditions. Task Group 72 (TG-72) from the American Association of Physicists in
51 Medicine [2] provides enough information for the physical aspects of the planning
52 process, such as room selection, potential shielding, acceptance, commissioning and
53 quality assurance.

54 One of the potential uncertainties or misadministration events in this technique is the
55 fluid instability in the post-resected surface [3]. It can be especially critical in surgery
56 beds with high-vascularized scenarios. Electron energy for treatment is selected
57 according to the specific depth of the target. Due to the high dose gradient after the
58 therapeutic range of electrons, if bleeding exists at the time of irradiation then a non-
59 desired target underdose can be produced. The adequate coverage of the target volume
60 plays a crucial role in a successful treatment. According to [1], 0.5 cm height of fluid
61 has been identified as the threshold for fluid detection.
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64 **II. MATERIAL AND METHODS**

65 *II.1 Mobile linac*

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68 LIAC HWL (SIT, Sordina IORT Technologies, Vicenza, Italy) is an intraoperative tool
69 for radiotherapy (IOERT) dedicated mobile linac specifically designed for executing
70 IOERT treatment inside a conventional operating room (OR).

71 LIAC HWL is available in two models, the 10 MeV model, with energy of 4, 6,
72 8 and 10 MeV, and 12 MeV model, with energy of 6, 8, 10 and 12 MeV; its dimensions
73 and weight allows its use without any modification and reinforcement of the OR floor.

74 The LIAC HWL commissioning process is very similar to LIAC, widely
75 discussed both for the experimental part [4–7] and for the Monte Carlo modelization
76 [7,8].

77 The equipment has been designed in order to reduce the stray radiation (SR) to a
78 minimum. This specific achievement has been pursued by reducing the interaction
79 between the accelerated electron beam and any metallic element, by means of the
80 development of a beam optic system. Such design has allowed to minimize the overall
81 SR: in the patient plane it results lower than 0.2 $\mu\text{Sv}/\text{Gy}$ at a distance of 3 m from the
82 target [9]. Therefore, according to NCRP 151 approach [10], the weekly workload is
83 higher than 100 Gy/week.

84 The choice of PMMA for the applicators allows both the possibility of
85 implementing hard docking and the direct visualization of the target to be irradiated
86 (Fig. 1). Two different applicator sets are available, with the same overall length but
87 different lengths of the terminals (lower applicator).

88 Applicators have diameters ranging from 3 to 12 cm with terminal bevel angles
89 ranging from 0° to 45°. Dose rate with reference applicator (10 cm diameter, bevel 0°)
90 can be adjusted in the range 10–30 Gy/min. The radiation treatment for typical doses up
91 to 20 Gy is completed in less than two minutes.

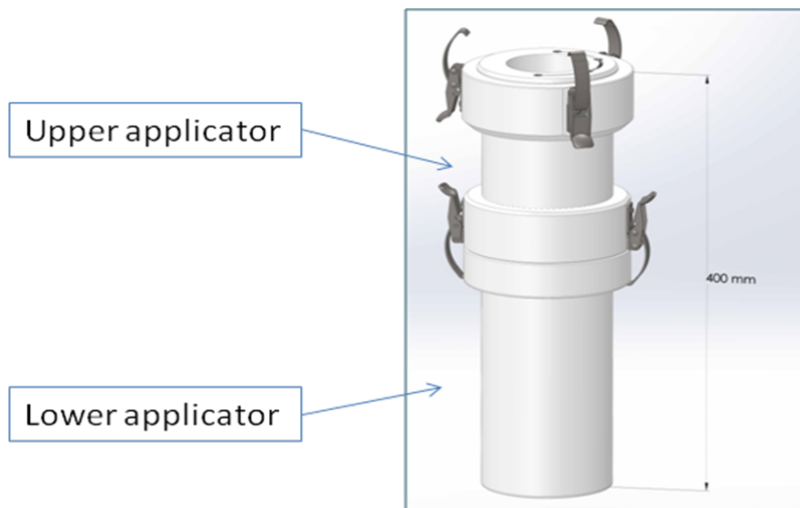


Fig. 1. LIAC HWL applicator.

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95 *II.2 Bleeding detector*

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97 The bleeding detector is based on a capacitive sensor. The main advantages of these
98 capacitive sensors being their low cost, low power consumption and linearity [11,12].
99 The bleeding detector is implemented by using two metallic strips made of copper
100 surrounding the bottom part of the applicator as shown in Fig. 2. The strips are placed
101 as close to the bottom surface as possible in order to provide a signal with the minimal
102 possible blood quantity. These strips act as a capacitor that enables changes in the
103 presence of liquid in the applicators.

104 The measurement process is based on repetitive charge–discharge cycles of the
105 capacitor through a resistor, performing a quasi-digital sensor. The discharging time is
106 measured through a microprocessor working in free-running mode. The chosen resistor
107 value of 20 M Ω is a satisfactory compromise between obtaining a good time resolution
108 and having enough statistics. Because each charge–discharge process is fast, it is
109 possible to continuously monitor the bleeding inside the applicator. In order to have
110 statistically significant measurements we monitorize the detector signal continuously at
111 a rate of 10 Hz.

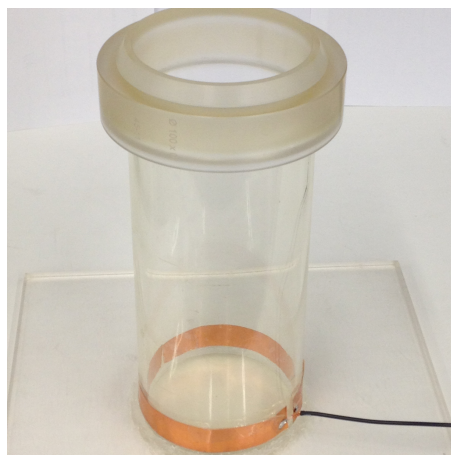
112 Fig. 3 shows the test bench that comprises the sensor, cabling, the
113 microprocessor for data acquisition and a computer.

114 The tests carried out so far have allowed the dimensions of the sensor to be
115 established in order to obtain a detectable signal while maintaining visibility through the
116 walls of the applicator. Specifically, the sensor is 0.02 cm thick, 2.0 cm high; the length
117 being dependent on each applicator and covering the entire perimeter with a gap of 0.5
118 cm at each end of the strip. Two tilting angles for the applicator 0° and 45° have been
119 considered. In both cases, the two strips surround the applicator perimeter and are
120 located at the end of the applicator.

121 For the connection between the sensor and the microprocessor a coax cable 70
122 cm long has been chosen. This length was chosen because it fits the distance between
123 the bottom part of the lower applicator and the LIAC’s HWL head where a
124 microprocessor is installed. As the system measures time differences, the added capacity
125 due to the coax cable introduces a bias that is not relevant for the measurements.

126 Measurements during intraoperative sessions will be done using a port of this
127 microprocessor connected through a RS-485 standard port to a computer located outside
128 the operating room. Thus, the system would operate as follows: once the applicator is
129 configured, the absence of blood is verified and the time reference as “zero condition” t_0

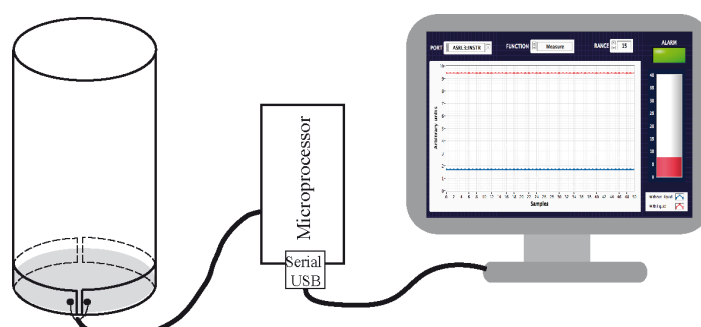
130 is acquired, showing its value on the computer. Later, after the preparation (fixation and
131 coupling), either the computer or the microprocessor processes the sensor signal
132 continuously and indicates the presence or absence of blood in the applicator. It is
133 possible for the system to operate in a yes/no decision mode or in a linear mode.
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Figure 2: Capacitive sensor located at the bottom part of the applicator.

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Figure 3: Block diagram of the test bench.

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141 *II.3. Detector sensitivity*

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143 To evaluate the detector sensitivity an experiment was developed using water
144 simulating blood at room temperature. In order to simulate the patient's breathing, we
145 have installed the detector on top of the Quasar Respiratory Motion Phantom from
146 Modus QA [13], which has been programmed at 16 bps to represent a worst scenario
147 baseline condition during the intraoperative intervention.

148

149 Taking into account that during clinical treatment both the LIAC HWL gantry angle
150 and the applicator bevel are selected according to the specific treatment site and the
151 patient anatomy, if bleeding exists it will accumulate partially in the field due to gravity.
152 Therefore, for testing, two setups employing the most typical applicator sizes used in
153 clinical procedures have been considered:

154

- 155 1. 7 cm diameter applicator with no bevel: 0° tilted, where the liquid has the same
156 height along the entire surface, and 45° tilted (highest bevel angle in practice),
157 where the liquid is accumulated in a corner.
- 158 2. 10 cm diameter applicator with no bevel: again, 0° tilted and 45° tilted.

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159 *II.4 Detector performance under radiation*

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One of the most important features of the mobile electron linacs is the low SR component, which facilitates its use in conventional surgery rooms. In fact, this feature has the greatest effect on the maximum workload in a specific room. The main contamination component is the x-rays produced by electron bremsstrahlung. As mentioned before, in case of the LIAC HWL this value is significantly low ($0.2 \mu\text{Sv}$ per administrated Gy at 3 m distance in patient plane), so it is necessary to evaluate whether the bleeding detector modifies this value or not. Consequently, the SR was evaluated with or without the bleeding detector for the worst-case energy (12 MeV) and for the 10 cm diameter applicator.

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The set-up used is shown in Fig. 4. The main reason that led us to define such set-up was to establish a minimum standard for the wall of any OR. It is also a thickness capable of shielding the low energy electrons escaping from the applicator as typically done in these types of measurements [14].

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The SR was measured using two different survey meters: Fluke INOVION 451 B and 451 P [15]. In this specific experiment, the aim was to evaluate whether extra SR is produced due to the strips of the fluid detector or not. Then, relative measurements were performed with the 10 cm diameter applicator with or without strips. The measurements were performed in integration mode delivering 500 monitor units (15 s) per each irradiation, repeating the irradiation three times in both setups. The statistical uncertainty of the resulting ratios was estimated as less than 5%.

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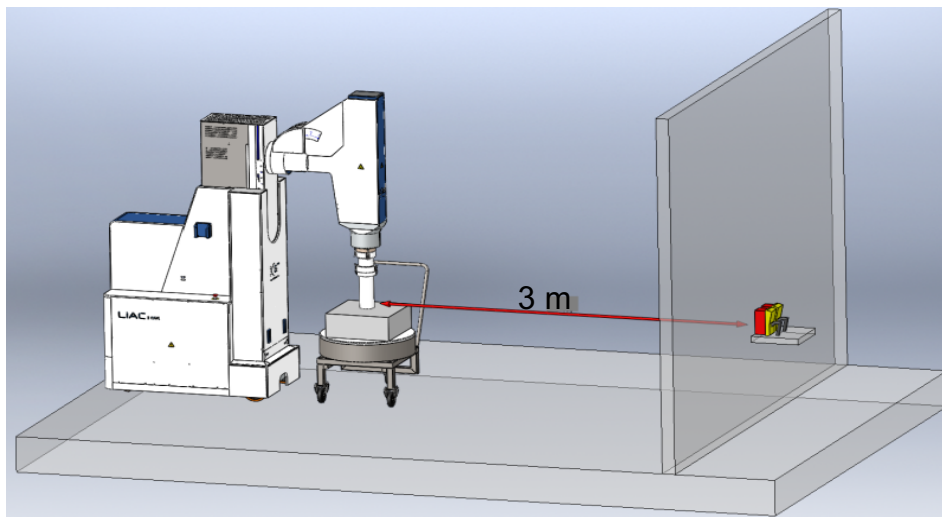
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On the other hand, the performance of the sensor was evaluated under radiation in order to classify it as either a pretreatment or permanent sensor. For this purpose, we used the LIAC HWL at the Sordina installations. Measurements were taken for different electron energies: the minimum (6 MeV) and maximum (12 MeV) for both setups. It has been checked for a liquid volume equivalent to a height of 1 cm for both setups.



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Figure 4: SR measurement set-up: SR is measured behind a 5 cm drywall layer at a distance of 3 m from the target.

197 **III. RESULTS**

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199 *III.1 Detector sensitivity*

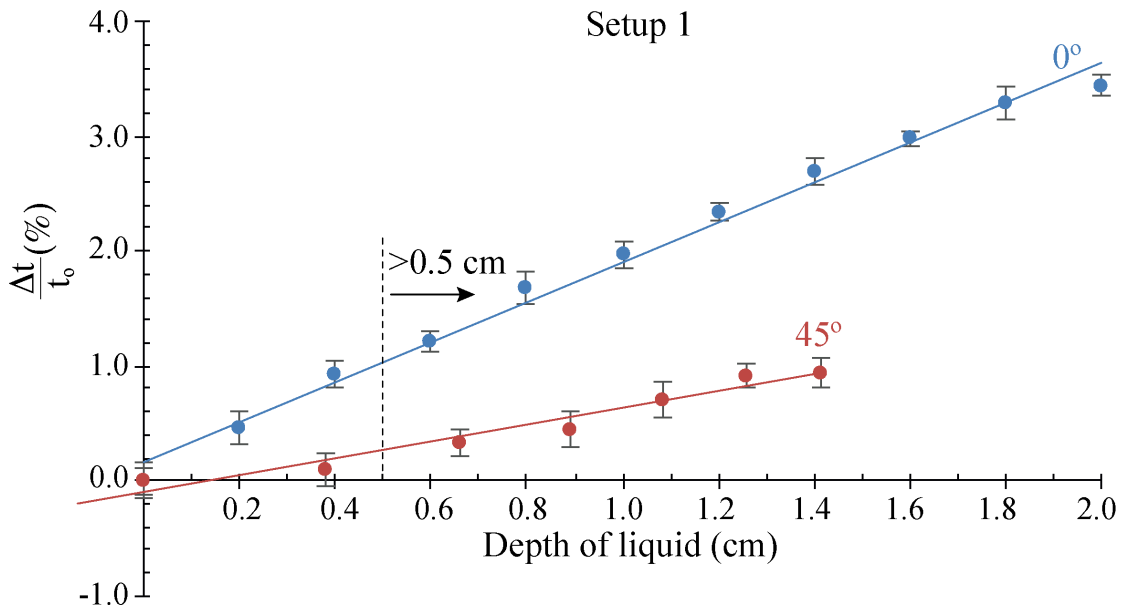
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201 Fig. 5 (setup 1) and Fig. 6 (setup 2) show the percentage variations of the
202 discharging time Δt with respect to the zero condition t_0 as a function of the depth of
203 liquid, measured with respect to the horizontal surface. The maximum value of liquid
204 depth shown in Fig. 5 and Fig. 6 is the one that, measured with respect to the horizontal
205 surface, equals the height of the sensor strip (i.e. 2 cm for the bevel 0° applicator and
206 1.4 cm for bevel 45°).

207 Fig. 5 shows the experimental results for setup 1, with the response of the
208 detector against the depth of liquid present in the 7 cm applicator, both for bevel 0°
209 (blue) and bevel 45° (red). Sensitivity is about 1.74 (%)/cm for the 7 cm diameter
210 applicator, bevel 0° , and about 0.73 (%)/cm for bevel 45° . The statistically expanded
211 uncertainty is 0.32%, coverage factor $k=2$.

212 Fig. 6 shows the experimental results for setup 2, with the response of the
213 detector against the height of liquid present in the 10 cm applicator, both for bevel 0°
214 (blue) and bevel 45° (red). Sensitivity is about 2.55 (%)/cm for the 10 cm diameter
215 applicator, bevel 0° , and about 1.64 (%)/cm for the same diameter applicator but bevel
216 45° . The statistically expanded uncertainty is 0.36%, coverage factor $k=2$.

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219 **Figure 5: Percentage variations of the time discharging Δt with respect to the zero condition t_0 vs**
220 **the depth of liquid for setup 1 (7 cm applicator diameter).**

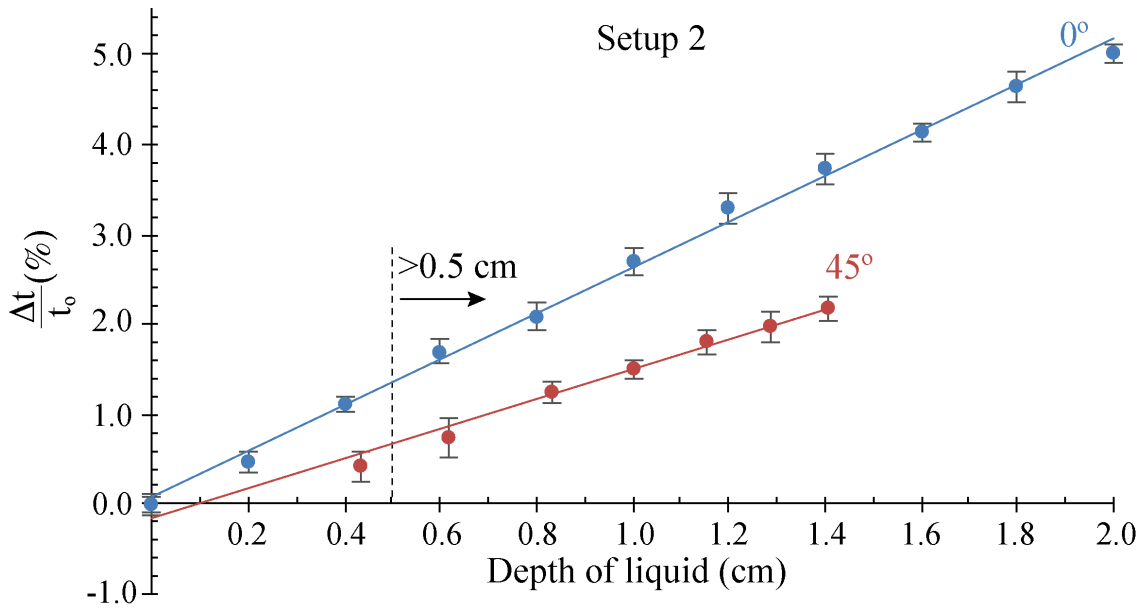
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Blue: bevel 0° . Red: bevel 45° .

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Error bars represent one standard deviation.

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225 **Figure 6. Percentage variations of the time discharging Δt with respect to the zero condition t_0 vs**
226 **the depth of liquid for setup 2 (10 cm applicator diameter).**

227 **Blue: bevel 0°. Red: bevel 45°.**

228 **Error bars represent one standard deviation.**

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230 *III.2 Detector performance under radiation*

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232 On the one hand, no variation of the SR was found in the measurements performed with
233 or without the detector. On the other hand, with respect to the performance of the
234 detector with or without radiation, the results obtained have shown invariability (in the
235 range of 0.4%).

236 The very minimal effect of the radiation over the detector is due to some peaks
237 observed during data taking due to the LIAC's HWL electromagnetic radiation (i.e.
238 mainly power supply switching). These peaks can easily be suppressed by software,
239 thus eliminating the effect.

240
241 **IV DISCUSSION**

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243 There are specific clinical scenarios (i.e. rectum, breast, prostate, gynaecological
244 recurrence, sarcomas, retroperitoneal, etc.) where the resulting bed to be irradiated can
245 be composed of highly vascular tissue with potential bleeding [1,16–20]. Although a
246 full sucked is done, the bleeding probability is not negligible. If bleeding occurs, the
247 thickness to be irradiated changes and, consequently, also changes the therapeutic range
248 of selected electrons energy, resulting in underdose of the deeper target layers.

249 Until now, the bleeding is controlled by looking through the transparent wall of
250 the applicator so there is no control when the applicator is partially covered with tissue.
251 When bleeding happens, typically the surgeon realizes it once the applicator is removed
252 after finishing the irradiation with no chance for correction. With the help of the
253 proposed detector this undesired effect is permanently controlled allowing for an
254 adjusted therapeutic range with the selected electron energy. To the best of our
255 knowledge, no other bleeding detector exists nor in the market nor in the literature.

256 In our opinion, the results are quite promising for liquid detection even in the
257 worst clinical scenario, i.e. minimum diameter applicator 45° tilt. As seen in Figs. 5 and
258 6, it is possible for both setups to clearly detect a depth of 0.5 cm of liquid accumulated

259 in the applicator, as required. We observed a dependence on the detector sensitivity with
260 the applicator diameter (i.e. the bigger the diameter of the applicator the greater the
261 sensitivity). Because of this, the uncertainty associated with the 0.5 cm depth value for
262 setup 1 (0.2 cm) is bigger than for setup 2 (0.1 cm). The response of the detector is
263 linear throughout the range of measurements for both setups.

264 The detector proposed and studied in this work is characterized by its low cost
265 and linear behavior between the amount of liquid present in the applicator and the
266 percentual deviation in the discharge time measured with respect to the so called zero
267 condition. The linearity observed in the behavior of the detector enables new
268 measurements to be used to determine, not only whether or not there is liquid present in
269 the applicator, but the amount of liquid present. This would offer advantages over the
270 single liquid detection option (yes/no) in any clinical scenario.

271 In a second phase of the study we will optimize the behavior of the sensor, i.e.
272 study of materials, dimensions and geometry.

273

274 **V CONCLUSIONS**

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276 A bleeding detector system has been developed that can be used from the
277 treatment preparation to the irradiation phase, which benefits it as a pre-treatment and
278 also a continuous detector, allowing to survey the bleeding along the whole clinical
279 procedure. The bleeding detector is performed using a quasi-digital capacitive sensor
280 with low-cost, low-power consumption, high linearity that is easy to install. The
281 detector is able to reveal the presence of a volume of liquid in the applicator
282 corresponding to a depth of water of 0.5 cm measured in the applicator, even in the
283 worst-case situation, i.e. 7 cm diameter applicator tilted 45°.

284 The detector can be used directly with plastic applicators, as is the case of LIAC
285 HWL, making it highly suitable for industrialization, as there is no need for additional
286 electronics in this specific linac. Given this, any future work would consist of the
287 integration of the sensor into the applicator body. Eventually, if needed, the coax cable
288 connecting the sensor to the microprocessor could be easily replaced by a standard
289 wireless communication.

290

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295 **Disclosure**

296 Giuseppe Felici, is an employee and shareholder of S.I.T. – Sordina IORT Technologies
297 SpA, Vicenza, Italy..

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